

February 20th-25th, 2011

SeisSol2D Workflow

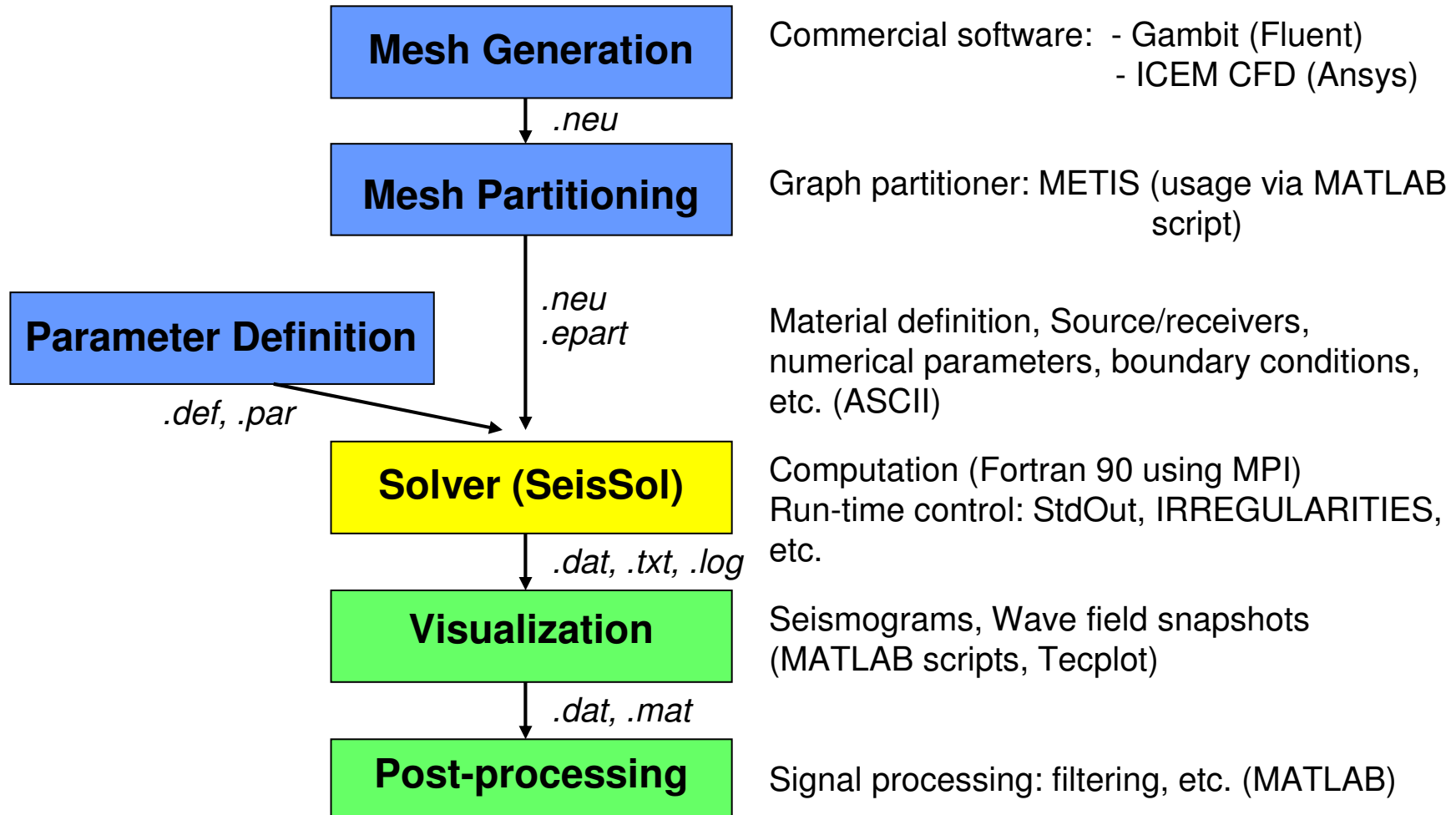
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Department of Earth and Environmental Sciences, LMU München, Germany

The SeisSol2D Source Code

- **numerical scheme:** **discontinuous Galerkin finite-elements**
- **programming language:** **mainly FORTRAN 90**
few FORTRAN 77 subroutines
- **number of subroutines:** **304**
- **number of files:** **54**
- **number of directories:** **3**
- **number of lines of source code:** **~ 50.000**
- **number of developers:** **~ 6**
- **pre-processing:** **mesh generation, mesh partitioning, parameterization, (e.g. material distribution, ...)**
- **post-processing:** **visualization of wave field (snapshots, seismograms), peak ground motion, stress distribution, seismic signal processing, ...**

The SeisSol Workflow



Discretization

What numerical methods do you know or have you heard of ?

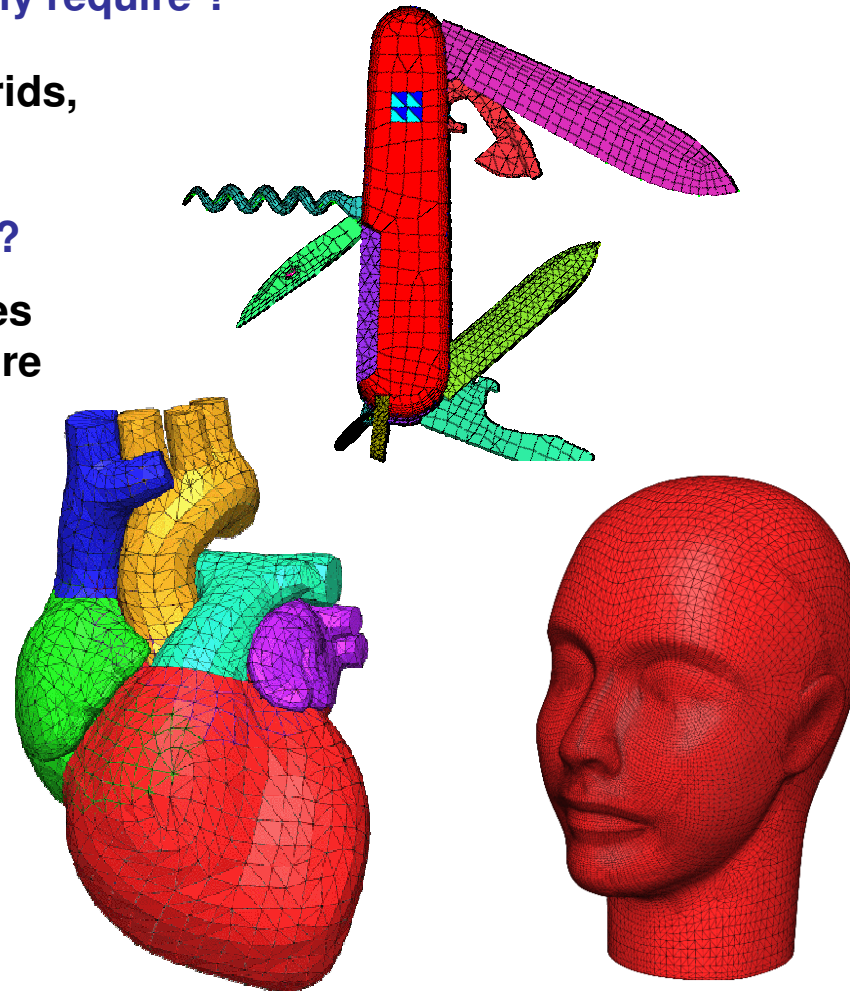
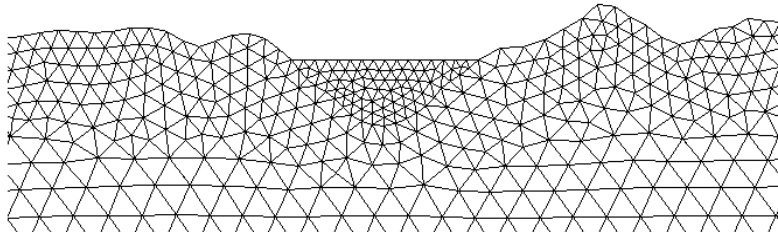
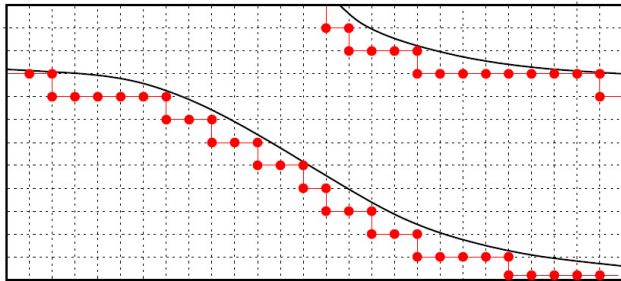
Finite Differences (FD), Finite Elements (FE), Finite Volumes (FV), etc.

What do numerical method usually require ?

points or particles, regular grids,
unstructured meshes, etc.

What is an “*unstructured mesh*” ?

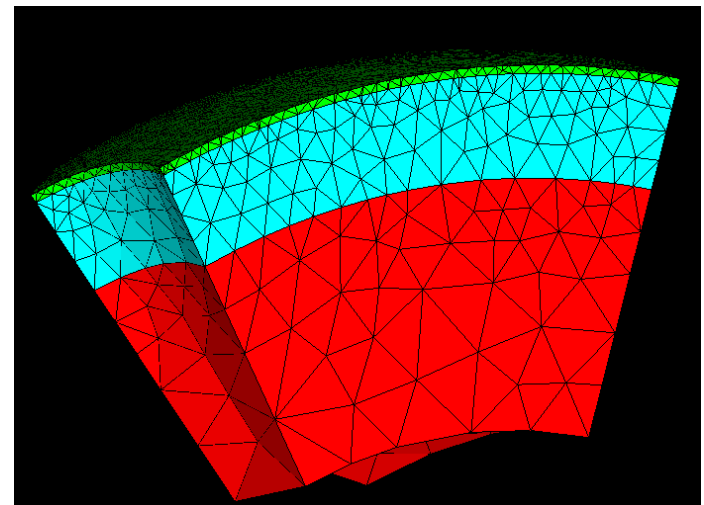
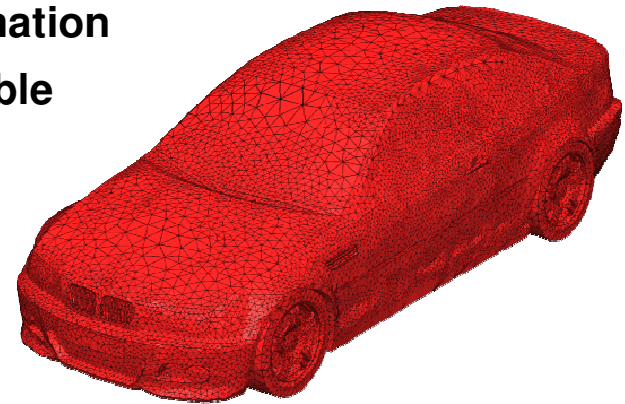
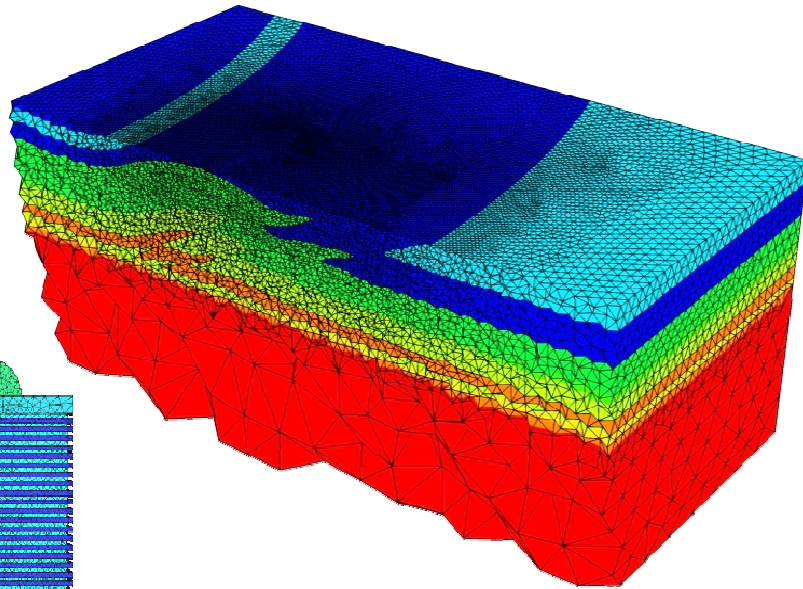
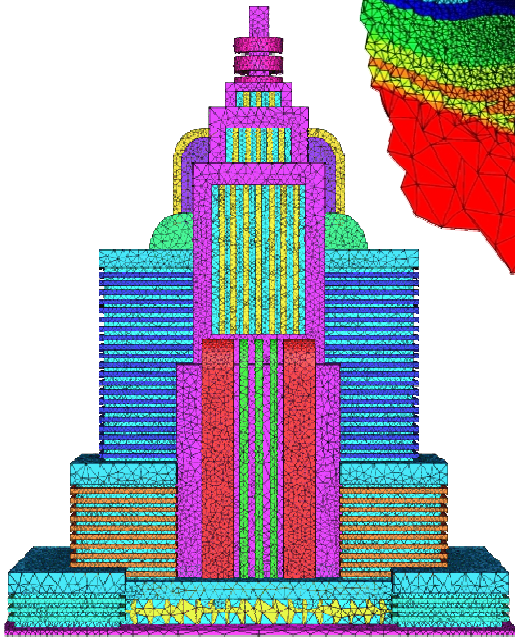
A mesh where element indices
do not show a logical structure



Discretization

The discretization subdivides a continuous physical model into a set of points, elements, control volumes, cells, etc.

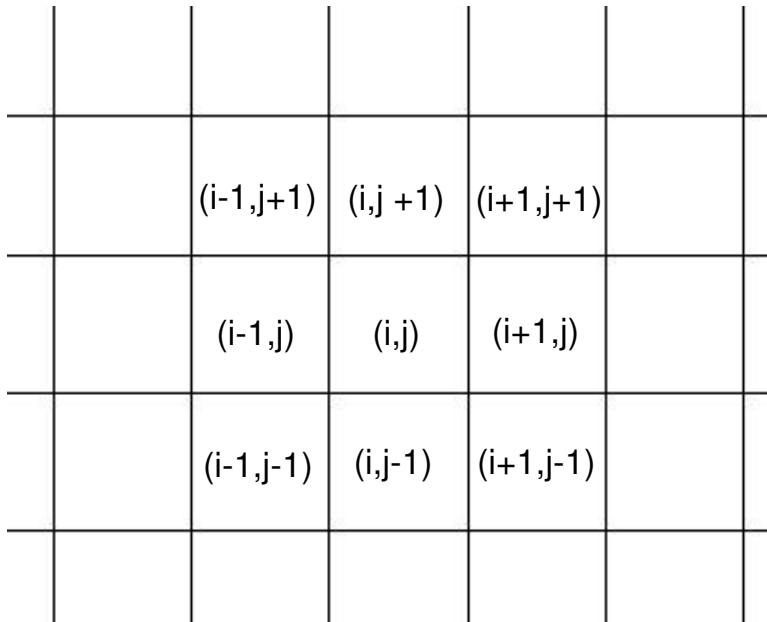
- numerical methods approximate functions discretely on these points or elements
- the finer the mesh, the more accurate the approximation
- unstructured meshes are geometrically more flexible



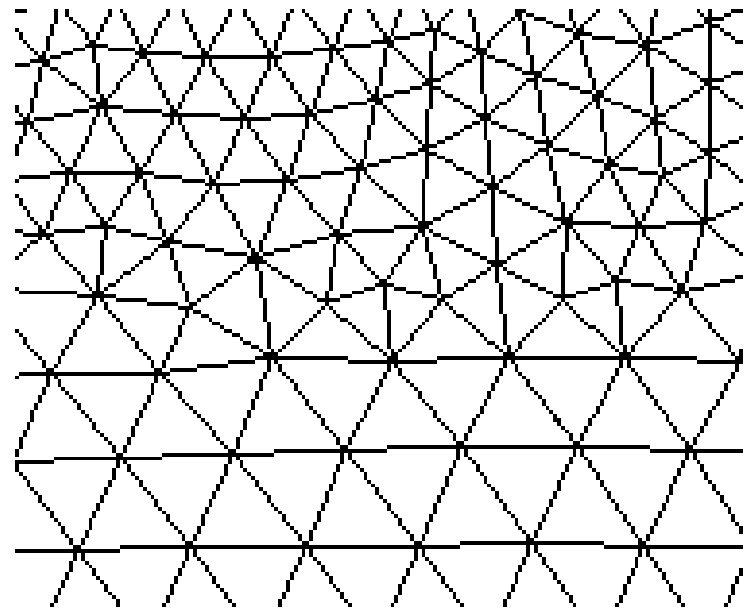
Discretization of a physical model in 2D

Discretization (= the process of Mesh Generation) can still be simple in 2D

→ we might still be able to use indices in a logical structure



But how do you distribute indices in this mesh and identify your neighbour ???



→ In structured meshes it is easy to know the neighbour elements to pass information

Connectivity matrix of meshes

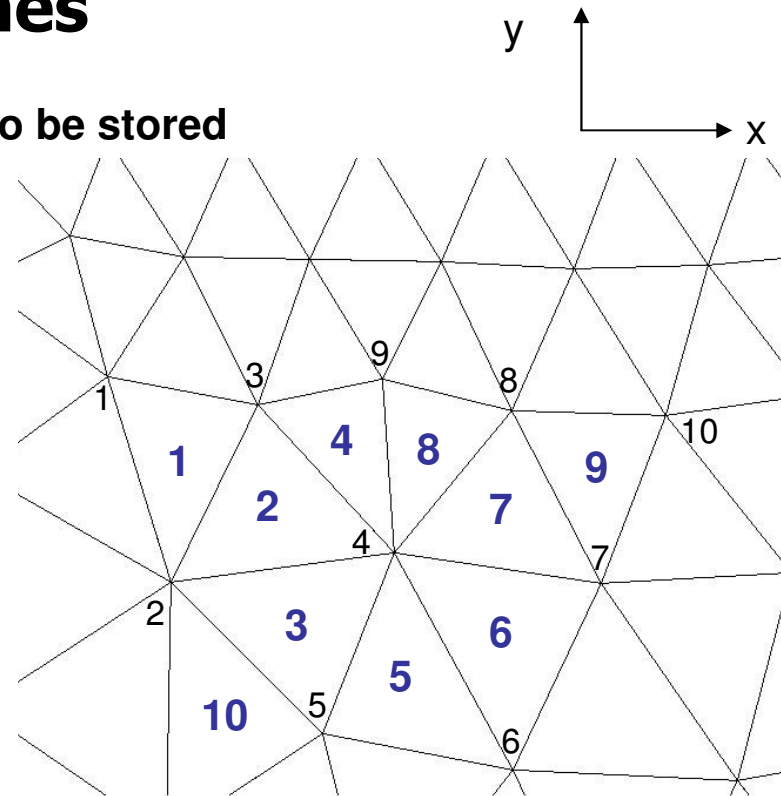
- in unstructured meshes, all vertices have to be stored
- the connectivity matrix defines elements

list of vertices

1	x_1	y_1
2	x_2	y_2
3	x_3	y_3
4	x_4	y_4
...	...	...

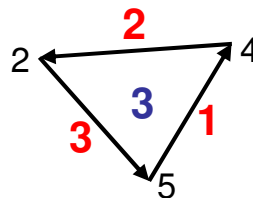
list of elements (= connectivity matrix)

1	1	2	3
2	2	4	3
3	5	4	2
4	4	9	3
5	5	6	4
6	6	7	4
7	4	7	8
8	9	4	8
9	8	7	10
...	...	...	...



Note : the **numbering of vertices** has to be oriented, e.g. here **counter-clockwise !!!**

→ this gives the edges that define the neighbours



list of neighbours

1	...	2	...
2	3	4	1
3	5	2	10
...	...	...	...
7	?	?	?
...	...	...	...

Connectivity matrix of meshes

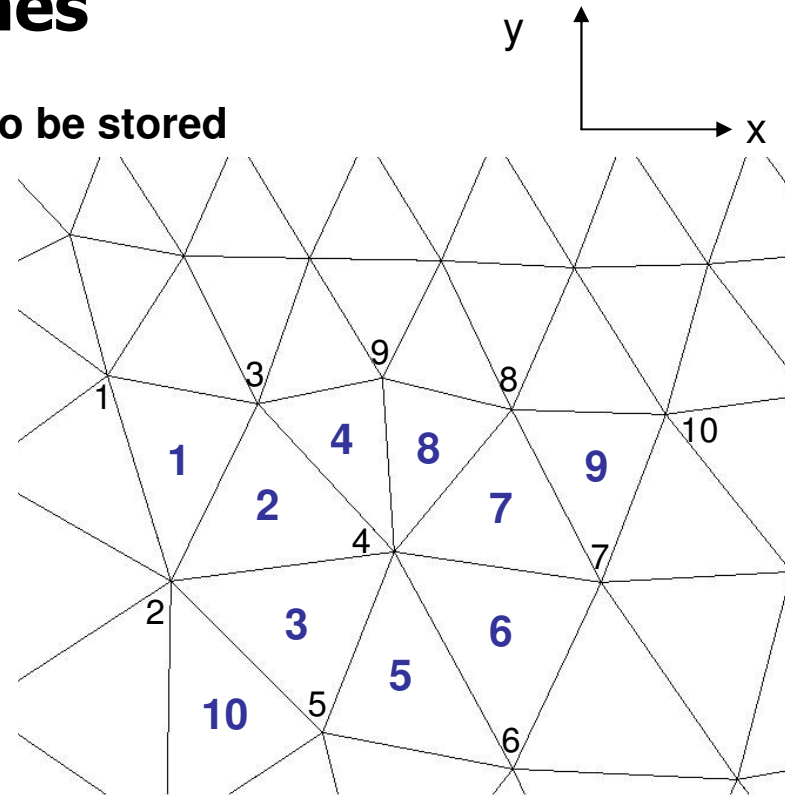
- in unstructured meshes, all vertices have to be stored
- the connectivity matrix defines elements

list of vertices

1	x_1	y_1
2	x_2	y_2
3	x_3	y_3
4	x_4	y_4
...	...	...

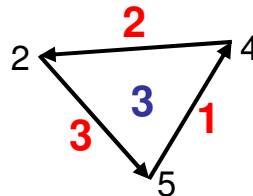
list of elements (= connectivity matrix)

1	1	2	3
2	2	4	3
3	5	4	2
4	4	9	3
5	5	6	4
6	6	7	4
7	4	7	8
8	9	4	8
9	8	7	10
...	...	...	...



Note : the **numbering of vertices** has to be oriented, e.g. here **counter-clockwise !!!**

→ this gives the edges that define the neighbours



list of neighbours

1	...	2	...
2	3	4	1
3	5	2	10
...	...	...	...
7	6	9	8
...	...	...	...

Connectivity matrix of meshes

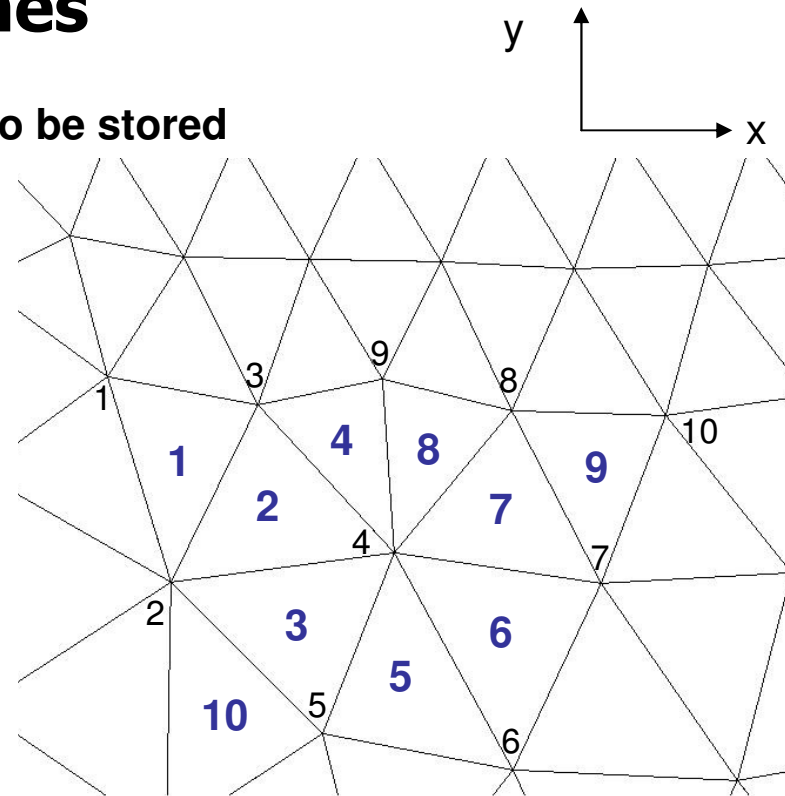
- in unstructured meshes, all vertices have to be stored
- the connectivity matrix defines elements

list of vertices

1	x_1	y_1
2	x_2	y_2
3	x_3	y_3
4	x_4	y_4
...	...	...

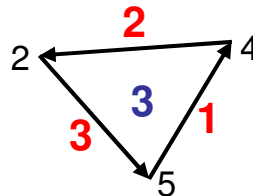
list of elements (= connectivity matrix)

1	1	2	3
2	2	4	3
3	5	4	2
4	4	9	3
5	5	6	4
6	6	7	4
7	4	7	8
8	9	4	8
9	8	7	10
...	...	...	...



Note : the **numbering of vertices** has to be oriented, e.g. here **counter-clockwise !!!**

→ this gives the edges that define the neighbours



list of neighbours

1	...	2	...
2	3	4	1
3	5	2	10
...	...	...	...
7	6	9	8
...	...	...	...

list of neighbour sides

1	...	3	...
2	2	3	2
3	3	1	...
...	...	...	...
7	?	?	?
...	...	...	...

Connectivity matrix of meshes

→ in unstructured meshes, all vertices have to be stored

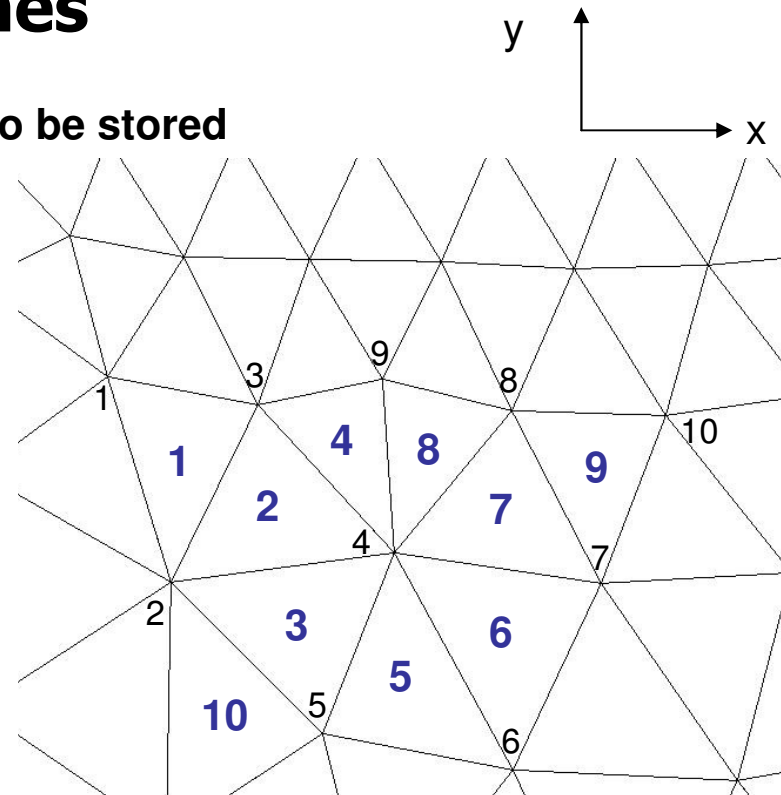
→ the connectivity matrix defines elements

list of vertices

1	x_1	y_1
2	x_2	y_2
3	x_3	y_3
4	x_4	y_4
...	...	...

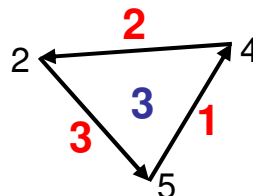
list of elements
(= connectivity matrix)

1	1	2	3
2	2	4	3
3	5	4	2
4	4	9	3
5	5	6	4
6	6	7	4
7	4	7	8
8	9	4	8
9	8	7	10
...	...	...	...



Note : the numbering of vertices has to be oriented, e.g. here counter-clockwise !!!

→ this gives the edges that define the neighbours



list of neighbours

1	...	2	...
2	3	4	1
3	5	2	10
...	...	...	...
7	6	9	8
...	...	...	...

list of neighbour sides

1	...	3	...
2	2	3	2
3	3	1	...
...	...	...	...
7	2	1	2
...	...	...	...

The Mesh File .neu

CONTROL INFO 2.3.16

** GAMBIT NEUTRAL FILE

basin

PROGRAM: Gambit VERSION: 2.3.16

Jan 2011

NUMNP	NELEM	NGRPS	NBSETS	NDFCD	NDFVL
909	1686	2	3	2	2

ENDOFSECTION

NODAL COORDINATES 2.3.16

1 -1.99632899778e+003 -1.93267624127e-012
2 9.85389565112e+003 1.13686837722e-013
3 -1.74944931759e+003 0.00000000000e+000
4 -1.50256963740e+003 0.00000000000e+000

...

907 -7.78723410147e+003 -3.07694414949e+003
908 -8.49870831127e+003 -3.55421101275e+003
909 -6.52218493125e+003 -3.91849972757e+003

ENDOFSECTION

ELEMENTS/CELLS 2.3.16

1	3	3	3	1	51
2	3	3	2	49	100
3	3	3	2	100	50
4	3	3	50	100	98

...

1685	3	3	903	906	900
1686	3	3	907	903	908

ENDOFSECTION

Header
information

The Mesh File .neu

CONTROL INFO 2.3.16

** GAMBIT NEUTRAL FILE

basin

PROGRAM: Gambit VERSION: 2.3.16

Jan 2011

NUMNP	NELEM	NGRPS	NBSETS	NDFCD	NDFVL
909	1686	2	3	2	2

ENDOFSECTION

NODAL COORDINATES 2.3.16

1 -1.99632899778e+003 -1.93267624127e-012
2 9.85389565112e+003 1.13686837722e-013
3 -1.74944931759e+003 0.00000000000e+000
4 -1.50256963740e+003 0.00000000000e+000

...

907 -7.78723410147e+003 -3.07694414949e+003
908 -8.49870831127e+003 -3.55421101275e+003
909 -6.52218493125e+003 -3.91849972757e+003

ENDOFSECTION

ELEMENTS/CELLS 2.3.16

1	3	3	3	1	51
2	3	3	2	49	100
3	3	3	2	100	50
4	3	3	50	100	98

...

1685	3	3	903	906	900
1686	3	3	907	903	908

ENDOFSECTION

Nodal coordinates

The Mesh File .neu

```
CONTROL INFO 2.3.16
** GAMBIT NEUTRAL FILE
basin
PROGRAM:          Gambit   VERSION: 2.3.16
Jan 2011
  NUMNP  NELEM  NGRPS  NBSETS  NDFCD  NDFVL
    909   1686    2     3     2     2
ENDOFSECTION
NODAL COORDINATES 2.3.16
  1 -1.99632899778e+003 -1.93267624127e-012
  2  9.85389565112e+003  1.13686837722e-013
  3 -1.74944931759e+003  0.00000000000e+000
  4 -1.50256963740e+003  0.00000000000e+000
  ...
 907 -7.78723410147e+003 -3.07694414949e+003
 908 -8.49870831127e+003 -3.55421101275e+003
 909 -6.52218493125e+003 -3.91849972757e+003
ENDOFSECTION
ELEMENTS/CELLS 2.3.16
  1 3 3    3    1    51
  2 3 3    2   49   100
  3 3 3    2   100   50
  4 3 3   50   100   98
  ...
1685 3 3   903   906   900
1686 3 3   907   903   908
ENDOFSECTION
```

Elements
= connectivity

The Mesh File .neu

```
CONTROL INFO 2.3.16
** GAMBIT NEUTRAL FILE
basin
PROGRAM:          Gambit   VERSION: 2.3.16
Jan 2011
  NUMNP  NELEM  NGRPS  NBSETS  NDFCD  NDFVL
    909   1686    2     3     2     2
ENDOFSECTION
NODAL COORDINATES 2.3.16
  1 -1.99632899778e+003 -1.93267624127e-012
  2  9.85389565112e+003  1.13686837722e-013
  3 -1.74944931759e+003  0.00000000000e+000
  4 -1.50256963740e+003  0.00000000000e+000
  ...
 907 -7.78723410147e+003 -3.07694414949e+003
 908 -8.49870831127e+003 -3.55421101275e+003
 909 -6.52218493125e+003 -3.91849972757e+003
ENDOFSECTION
ELEMENTS/CELLS 2.3.16
  1 3 3 3 1 51
  2 3 3 2 49 100
  3 3 3 2 100 50
  4 3 3 50 100 98
  ...
1685 3 3 903 906 900
1686 3 3 907 903 908
ENDOFSECTION
```

Elements
= connectivity

Element identifier
(not important)

The Mesh File .neu

```
ELEMENT GROUP 2.3.16
GROUP:      1 ELEMENTS:    300 MATERIAL:      4 NFLAGS:      1
            basin
      0
      1    2    3    4    5    6    7    8    9   10
     11   12   13   14   15   16   17   18   19   20
      ...
     281   282   283   284   285   286   287   288   289   290
     291   292   293   294   295   296   297   298   299   300
ENDOFSECTION

ELEMENT GROUP 2.3.16
GROUP:      2 ELEMENTS:   1386 MATERIAL:      4 NFLAGS:      1
            bedrock
      0
     301   302   303   304   305   306   307   308   309   310
     311   312   313   314   315   316   317   318   319   320
      ...
    1671   1672   1673   1674   1675   1676   1677   1678   1679   1680
    1681   1682   1683   1684   1685   1686
ENDOFSECTION
```

Elements in
basin

The Mesh File .neu

ELEMENT GROUP 2.3.16

GROUP: 1 ELEMENTS: 300 MATERIAL: 4 NFLAGS: 1
basin

0

1 2 3 4 5 6 7 8 9 10
11 12 13 14 15 16 17 18 19 20

...

281 282 283 284 285 286 287 288 289 290
291 292 293 294 295 296 297 298 299 300

ENDOFSECTION

ELEMENT GROUP 2.3.16

GROUP: 2 ELEMENTS: 1386 MATERIAL: 4 NFLAGS: 1
bedrock

0

301 302 303 304 305 306 307 308 309 310
311 312 313 314 315 316 317 318 319 320

...

1671 1672 1673 1674 1675 1676 1677 1678 1679 1680
1681 1682 1683 1684 1685 1686

ENDOFSECTION

Elements in
bedrock

The Mesh File .neu

```

BOUNDARY CONDITIONS 2.3.16
106 1 18 0 6
928 3 2
946 3 2
...
948 3 3
934 3 3
ENDOFSECTION
BOUNDARY CONDITIONS 2.3.16
105 1 40 0 6
932 3 3
942 3 3
...
940 3 2
930 3 2
ENDOFSECTION
BOUNDARY CONDITIONS 2.3.16
101 1 72 0 6
927 3 1
944 3 3
...
938 3 2
933 3 1
ENDOFSECTION

```

Boundary conditions

Identifier of boundary element type:

101 = free surface	boundary
102 = non-conforming	boundary
103 = dynamic rupture	boundary
104 = inflow	boundary
105 = absorbing	boundary
106 = periodic	boundary

Index of boundary element

Index of local side of the boundary element that carries the boundary condition

Mesh Partitioning with METIS:

You can get the mesh partitioner METIS as free-ware from:
<http://glaros.dtc.umn.edu/gkhome/views/metis>

After installation you have to extract the **connectivity matrix** from the mesh file (e.g. **basin.neu**) and put a simple **header** to identify the number of element and the element type:

1 = triangle

4 = quadrilateral

and save it as a METIS file, e.g. **basin.met**

basin.met

1686	1	
3	1	51
2	49	100
2	100	50
50	100	98
...		
903	906	900
907	903	908

First transform the mesh to a graph via the command

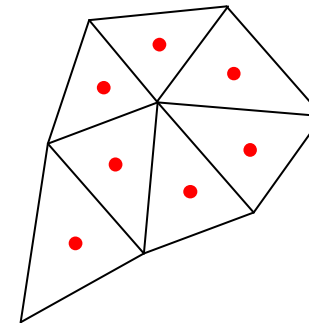
mesh2dual basin.met

Then partition the graph into the desired number **np** of processors (= subdomains) via the command

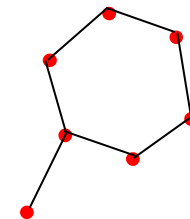
pmetis basin.met.dgraph np

and get the resulting file

basin.met.epart.np



mesh



graph

The Parameter File .par

The parameter file (typically with suffix **.par**) contains 12 blocks:

- SeisSol Version
- Equations
- Initial Condition
- Boundaries
- Source Terms
- Sponge Layer
- Mesh
- Discretization
- Output
- Abort Criteria
- Analysis of Data
- Debugging Modus

All simulation parameters are defined in the **.par** file.

The **.par** file will be discussed in detail during the excercises!

How to get and setup the seissol2d code:

Execute the following command (for SeisSol group members):

```
svn checkout https://user@svn.geophysik.uni-muenchen.de/svn/seissol2d/trunk
```

This will create a folder **trunk** in the directory, where you executed the command.

Within the folder **trunk** you will find the following subdirectories:

[./common](#)

[./main](#)

[./Maple](#)

[./Matlab](#)

[./src](#)

Create a new directory **[./examples](#)** for your own applications by

```
mkdir examples
```

How to compile the seissol2d code (1):

Make sure you have the [Intel compiler](#) available:
Follow the description on our [intranet](#) web-pages

[intranet](#) → [IT Service/HowTo's](#) → [Applications](#) → [Intel Software](#)

for I386 and AMD 64 machines.

[Linux/Windows](#)
[Mailing Lists](#)
[Subversion](#)
[Tools](#)
[Website](#)
[Telephone Manuals](#)
[Printing](#)
[Miscellaneous](#)
[Contact All](#)
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[Info for Newbies](#)
[In Case Of Emergency](#)

BASH Users

Please add the lines for the software product you need to your ~/.bash_profile:

Intel C/C++ and FORTRAN Compiler and Debugger

- on [I386](#) machines

```
# Intel C/C++ and FORTRAN Compiler and Debugger
if [ $(uname -m) = "i686" -a -e /opt/intel/Compiler/11/bin/iccvars.s
    source /opt/intel/Compiler/11/bin/iccvars.sh ia32
fi
```

- on AMD64 machines

```
# Intel C/C++ and FORTRAN Compiler and Debugger
if [ $(uname -m) = "x86_64" -a -e /opt/intel/Compiler/11/bin/iccvars
    source /opt/intel/Compiler/11/bin/iccvars.sh intel64
fi
```

- the C/C++ and FORTRAN Compiler and Debugger documentation is installed in /opt/intel/Compiler/11/Documentation/

How to compile the seissol2d code (2):

Make sure you have the [Intel MPI](#) available:

Follow the description on our [intranet](#) web-pages

[intranet](#) → [IT Service/HowTo's](#) → [Applications](#) → [Intel Software](#)

for I386 and AMD 64 machines.

Intel MPI

- on I386 machines

```
# Intel MPI
if [ $(uname -m) = "i686" -a -e /opt/intel/impi/3.2/bin/mpivars.sh
source /opt/intel/impi/3.2/bin/mpivars.sh
fi
```

- on AMD64 machines

```
# Intel MPI
if [ $(uname -m) = "x86_64" -a -e /opt/intel/impi/3.2/bin64/mpivars
source /opt/intel/impi/3.2/bin64/mpivars.sh
fi
```

- the MPI documentation is installed in /opt/intel/impi/3.2/doc/

How to compile the seissol2d code (3):

If your setup is correct, go to the `./main` directory and type:

`make clean`

`make`

After a successful compilation ending with

...

=====

=====

= installed `./../bin/seissol2dxx`

=====

=====

additional directories should have been created:

`./lib`

`./bin`

where `./bin` contains the executable

`seissol2dxx`

How to run a SeisSol simulation:

To run a simulation go to your working directory, e.g.

`./examples/basin`

and start the simulation with e.g.

`./seissol2dxx basin.par`

or on a cluster system (i.e. TETHYS)

`mpirun.openmpi -np 32 -nolocal -machinefile TETHYS.machines.32.G1 seissol2dxx basin.par`

that uses the executable `seissol2dxx`

on 32 cores defined in `TETHYS.machines.32.G1`

and the simulation parameters defined in `basin.par`

Output files generated by a SeisSol simulation:

Each core writes its

log-file:

IRREGULARITIES.0000.log

number of core

progress-file:

StdOut0000.txt

number of receiver

seismograms:

output-pickpoint-00001-0000.dat

(= time series of seismic ground motion at one position in space)

snapshots:

output-000000000.0000.tri.dat

number of time step

(= spatial slice of seismic ground motion on **mesh vertices** at one position in time)

snapshots fine-output:

output.GF.000000000.0000.dat

(= spatial slice of seismic ground motion as **polynomial coefficients in each element** at one position in time)

➔ the snapshot fine-output has to be **post-processed** for visualization on an **additional, regular, fine visualization grid**

➔ the post-processing is done with **dgvisuxx**

How to visualize SeisSol simulation results:

The main results from a SeisSol simulation are:

- seismograms (= time series of seismic ground motion at one position in space)
- snapshots (= spatial slice of seismic ground motion at one position in time)
- fine snapshots (= spatial slice of seismic ground motion at one position in time on a fine visualization mesh)

All output is generated in **tecplot**-format, remotely available through the LRZ.

Alternatively, **Gnuplot**, **Python** or **matlab**-scripts can be used for visualization.

Provided matlab-scripts in the repository:

for seismograms:

- [Reformat_seissol_seismograms.m](#)
- [Plot_seissol_seismograms.m](#)

(→ data reduction!)

for snapshots: [Plot_seissol_snapshot.m](#)

for fine snapshots: `Plot_seissol_snapshot_fine.m` (→ after post-processing with `dgvisuuxx`)

Post-Processing of Galerkin Fine (GF) output:

The Galerkin Fine (GF) output contains the **polynomial coefficients** of the approximation for every element.

Therefore, the **resolution can be much higher** through the element-internal structure of the wave field than for the normal snapshot output.

dgvisuxx is a tool to evaluate the polynomial approximation on a user-defined regular visualization grid

The required input file (e.g. **visu_basin.in**) can have the following form:

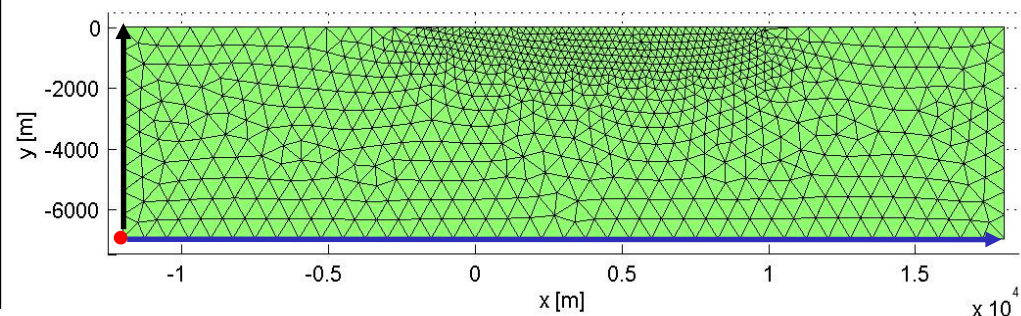
1	! Cartesian mode (yes=1)
-12000. -7000. 0.	! Coordinates of origin
30000. 0. 0.	! Vector of 1st Cartesian axis
0. 7000. 0.	! Vector of 2nd Cartesian axis
400	! Number of samples on 1st axis
100	! Number of samples on 2nd axis
1	! MPI input data (no=0, yes=1)
32	! Number of CPUs
output.GF.000000000	! MPI root filename
GF_basin.dat	! Output file name
1	! Output format (Tecplot=1)
sigma_xx	! Variable name 1
sigma_yy	! Variable name 2
sigma_xy	! Variable name 3
u	! Variable name 4
v	! Variable name 5
0	! End of file indicator

Create a file called DGPATH in your working directory, containing the absolute path to your Maple directory, e.g.

/home/messuser/seissol2d/Maple/

Then execute the post-processing via:

./dgvisuxx < visu_basin.in



Visualize data:

To visualize the seismograms (*-pickpoint-00001.dat) you can either use Python or simply gnuplot.

Start gnuplot with

gnuplot

The command to plot the second column against the time is

plot '***-pickpoint-00001.dat' u 1:2 w l**

Visualize data:

To visualize the snapshots which include mesh information use:

```
./visz_snap.py
```

as follows:

```
./visz_snap.py output-000000000.tri.dat
```

You produce a readable fine-output that respects the high-order polynomials with:

```
./dgvisuxx < visu.in
```

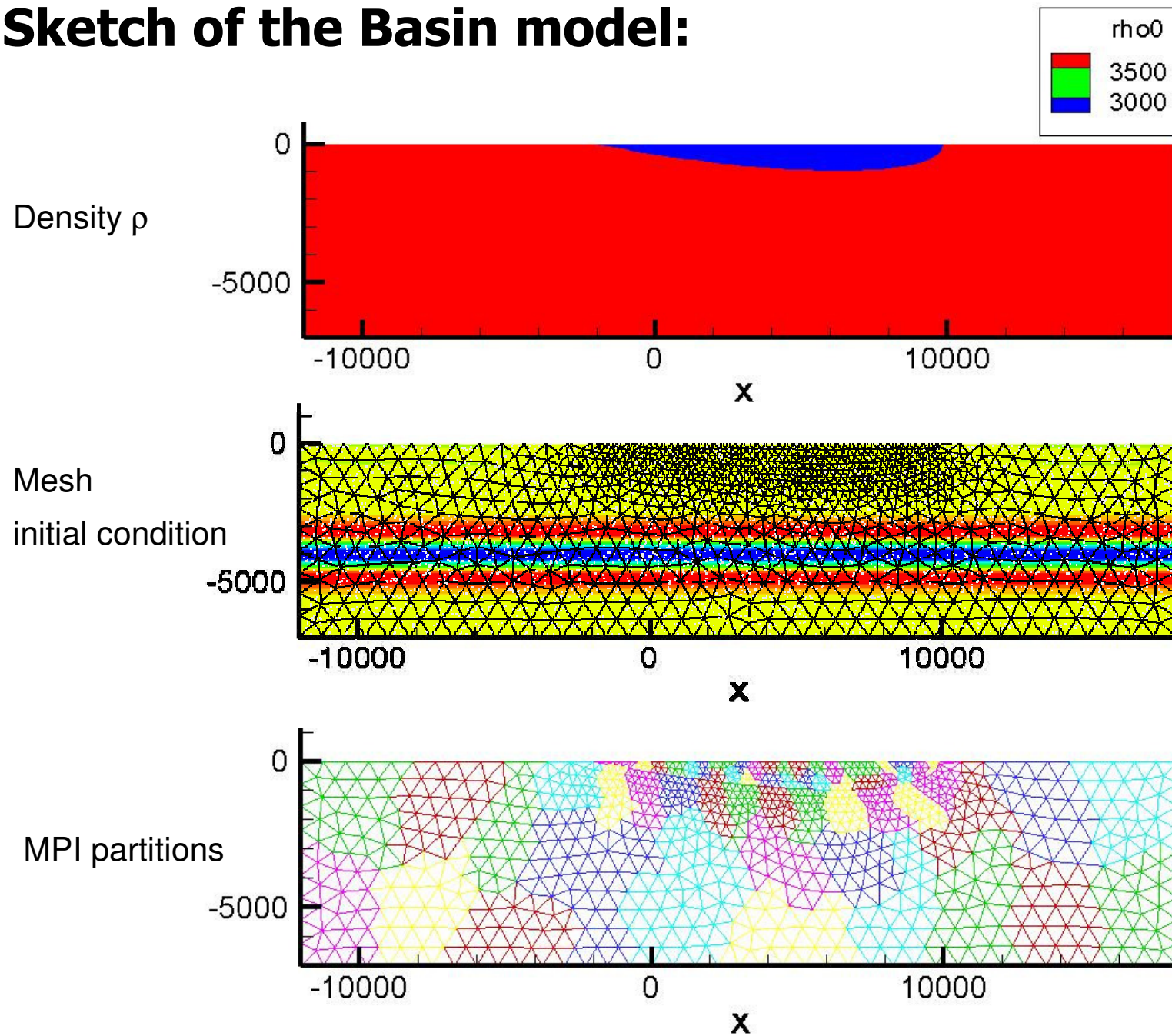
The result

```
GF_output_t0.dat
```

can be visualized with

```
./visz_fine.py GF_output_t0.dat
```

Sketch of the Basin model:



What will I find in my seissol2d folder?

/bin

- Contains the executables

/examples

- Contains the example models and setups
- your working directory

/Maple

- Contains the basis functions

/seissol2d_demo

- Source code

/seissol_papers

- Fundamental publications

/visualization

- Contains the visualization tools

seissol_course.pdf

seissol2d_workflow.pdf

seissol2d_docu.pdf



Seissol_practicals.pdf